Running a steeple chase

In class on Wednesday, we examined a SteepleChase program that allows Karel to run a "Steeple Chase" (like a hurdles race, but with arbitrarily large hurdles) where:

- Karel starts at position (1, 1), facing East.
- The steeple chase is guaranteed to be 9 avenues long.
- There can be arbitrarily many hurdles that can be of arbitrary size, located between any two avenues in the world.
- Karel should "jump" each hurdle one at a time.

For example, if you were to execute the SteepleChase program, you would see something like the following before-and-after diagram:

Below is the program listing of the SteepleChase program, which provides an example of various control structures in Karel, program decomposition, and comments (including the specification of pre- and post-conditions).
import stanford.karel.*;

public class SteepleChase extends SuperKarel {

    public void run() {
        for (int i = 0; i < 8; i++) {
            if (frontIsClear()) {
                move();
            } else {
                jumpHurdle();
            }
        }
    }

    private void jumpHurdle() {
        ascendHurdle();
        move();
        descendHurdle();
    }

    private void ascendHurdle() {
        turnLeft();
        while (rightIsBlocked()) {
            move();
        }
        turnRight();
    }
}
Creating a line of beepers
Consider the problem of writing a method `createBeeperLine`, which creates a line of beepers beginning at Karel’s current corner and proceeding forward to the next wall. For example, if you were to execute `createBeeperLine` in an empty world, you would see something like the following before-and-after diagram:

![Before and After Diagram](image)

The problem is slightly harder than it looks. Unless you think carefully about the problem, it is easy to find yourself making a common programming error that keeps the program from working as you’d like. For example, we might initially be inclined to solve the problem as follows:

```java
private void createBeeperLine() {
    while (frontIsClear()) {
        putBeeper();
        move();
    }
}
```
The problem here (as indicated by the "bug" picture next to the code), is that Karel will not place a beeper on the last corner he encounters. When he reaches the final corner of the row he's in, his front will no longer be clear, so the while loop will immediately exit before a beeper is placed on that final corner. This is perhaps easier to see when looking at the Karel's world after he executes the code above:

Note that in the picture above, there is no beeper on the corner that Karel is standing on. To solve this example of a "fence-post" problem (such problems are further discussed in the Karel course reader), we must make one more putBeeper() method call than calls to move(), as shown below:

```java
private void createBeeperLine() {
    while (frontIsClear()) {
        putBeeper();
        move();
    }
    putBeeper();
}
```

Cleaning up scattered beepers

Unfortunately, sometimes Karel's world gets a little messy, with beepers strewn around at various corners. We want to help Karel clean up his world by writing a program that has Karel go through the world and pick up any beepers that may be scattered about. We assume that:

- Karel starts at corner (1, 1) facing East
- Each corner of Karel's world may either be empty or contain at most one beeper, and when Karel is done there should be no more beepers on any corner
- Karel can finish his task at any location and orientation

If you were to execute your program, you would see something like the following before-and-after diagram on the next page.
Below is the program listing of the `CleanupKarel` program.

```java
import stanford.karel.*;

public class CleanupKarel extends SuperKarel {
    // Cleans up a field of beepers, one row at a time
    public void run() {
        cleanRow();
        while (leftIsClear()) {
            repositionForRowToWest();
            cleanRow();
            if (rightIsClear()) {
                repositionForRowToEast();
                cleanRow();
            } else {
                turnAround();
            }
        }
    }
}
```
 Doubling the number of beepers in a pile

Interestingly enough, Karel can also do various kinds of math. For example, we can ask Karel to double the number of beepers on some corner in the world. We'd like to write a program where there is a pile of some (finite) number of beepers on the corner directly in front of Karel. We want Karel to double the number of beepers in that pile and return to his original location and orientation. You can assume that Karel begins with an infinite number of beepers in his beeper bag.

For example, if you were to execute your program in the sample Before world shown below, you would expect to see the corresponding After world (note that the number of beepers on corner (2, 1) has been doubled):

![Before world](image1)

![After world](image2)
Below is the program listing of the **DoubleBeepers** program.

```java
/*
* File: DoubleBeepers.java
* ------------------------
* Karel doubles the number of beepers on the corner directly
* in front of him in the world. He then returns to his
* original position/orientation.
*/
import stanford.karel.SuperKarel;
public class DoubleBeepers extends SuperKarel {

    public void run() {
        move();
        DoubleBeepersInPile();
        moveBackward();
    }

    /*
    * For every beeper on the current corner, Karel places
    * two beepers on the corner immediately ahead of him.
    */
    private void DoubleBeepersInPile() {
        while (beepersPresent()) {
            pickBeeper();
            PutTwoBeepersNextDoor();
        }
        MovePileNextDoorBack();
    }

    /*
    * Place two beepers on corner one avenue ahead of Karel
    * and move back to starting position/orientation
    */
    private void PutTwoBeepersNextDoor() {
        move();
        putBeeper();
        putBeeper();
        moveBackward();
    }

    /*
    * Move all the beepers on the corner in front of Karel
    * the the corner Karel is currently on.
    */
    private void MovePileNextDoorBack() {
        move();
        while (beepersPresent()) {
            MoveOneBeeperBack();
        }
        moveBackward();
    }
}
```
/*
 * Move one beeper from the current corner back one avenue
 * and return to the original position/orientation.
 */
private void MoveOneBeeperBack() {
    pickBeeper();
    moveBackward();
    putBeeper();
    move();
}

/*
 * Move Karel back one avenue, but have the same
 * final orientation.
 */
private void moveBackward() {
    turnAround();
    move();
    turnAround();
}