

# Lecture 15

## Symmetric matrices, quadratic forms, matrix norm, and SVD

- eigenvectors of symmetric matrices
- quadratic forms
- inequalities for quadratic forms
- positive semidefinite matrices
- norm of a matrix
- singular value decomposition

# Eigenvalues of symmetric matrices

suppose  $A \in \mathbf{R}^{n \times n}$  is symmetric, *i.e.*,  $A = A^T$

**fact:** the eigenvalues of  $A$  are real

to see this, suppose  $Av = \lambda v$ ,  $v \neq 0$ ,  $v \in \mathbf{C}^n$

then

$$\bar{v}^T Av = \bar{v}^T (Av) = \lambda \bar{v}^T v = \lambda \sum_{i=1}^n |v_i|^2$$

but also

$$\bar{v}^T Av = \overline{(Av)}^T v = \overline{(\lambda v)}^T v = \bar{\lambda} \sum_{i=1}^n |v_i|^2$$

so we have  $\lambda = \bar{\lambda}$ , *i.e.*,  $\lambda \in \mathbf{R}$  (hence, can assume  $v \in \mathbf{R}^n$ )

# Eigenvectors of symmetric matrices

**fact:** there is a set of orthonormal eigenvectors of  $A$ , *i.e.*,  $q_1, \dots, q_n$  s.t.  
 $Aq_i = \lambda_i q_i$ ,  $q_i^T q_j = \delta_{ij}$

in matrix form: there is an orthogonal  $Q$  s.t.

$$Q^{-1}AQ = Q^T AQ = \Lambda$$

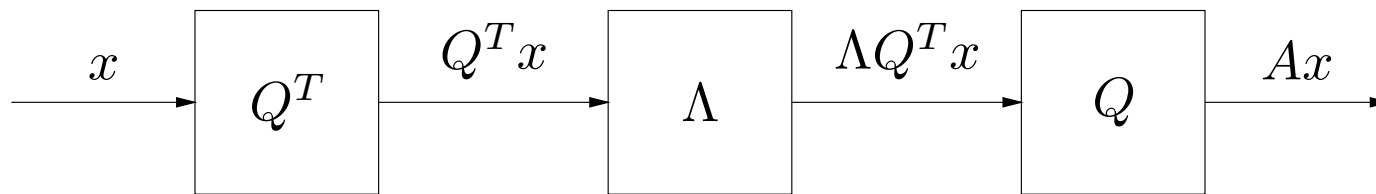
hence we can express  $A$  as

$$A = Q\Lambda Q^T = \sum_{i=1}^n \lambda_i q_i q_i^T$$

in particular,  $q_i$  are both left and right eigenvectors

# Interpretations

$$A = Q\Lambda Q^T$$



linear mapping  $y = Ax$  can be decomposed as

- resolve into  $q_i$  coordinates
- scale coordinates by  $\lambda_i$
- reconstitute with basis  $q_i$

or, geometrically,

- rotate by  $Q^T$
- diagonal real scale ('dilation') by  $\Lambda$
- rotate back by  $Q$

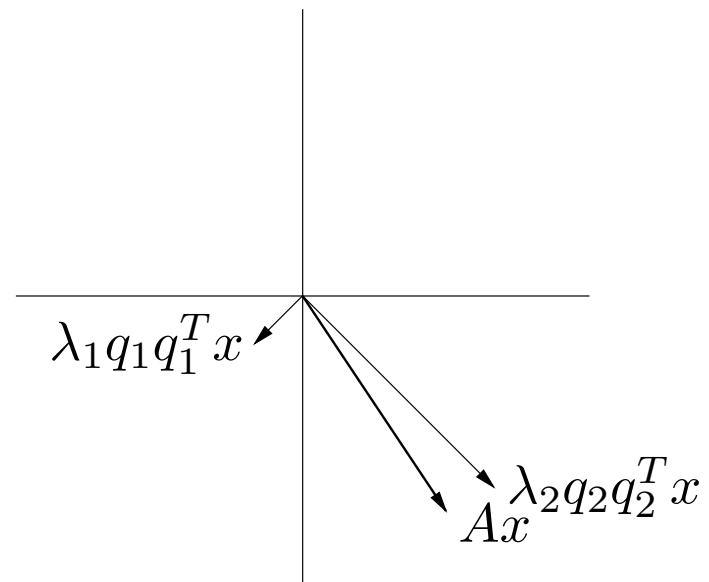
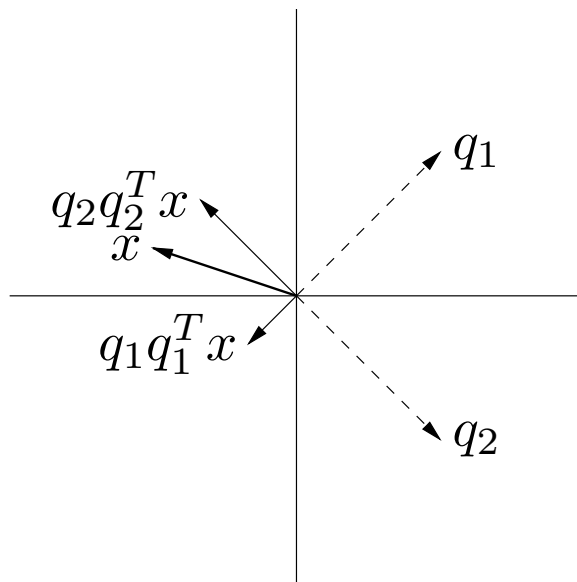
decomposition

$$A = \sum_{i=1}^n \lambda_i q_i q_i^T$$

expresses  $A$  as linear combination of 1-dimensional projections

**example:**

$$\begin{aligned} A &= \begin{bmatrix} -1/2 & 3/2 \\ 3/2 & -1/2 \end{bmatrix} \\ &= \left( \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \right) \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \left( \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \right)^T \end{aligned}$$



**proof** (case of  $\lambda_i$  distinct)

suppose  $v_1, \dots, v_n$  is a set of linearly independent eigenvectors of  $A$ :

$$Av_i = \lambda_i v_i, \quad \|v_i\| = 1$$

then we have

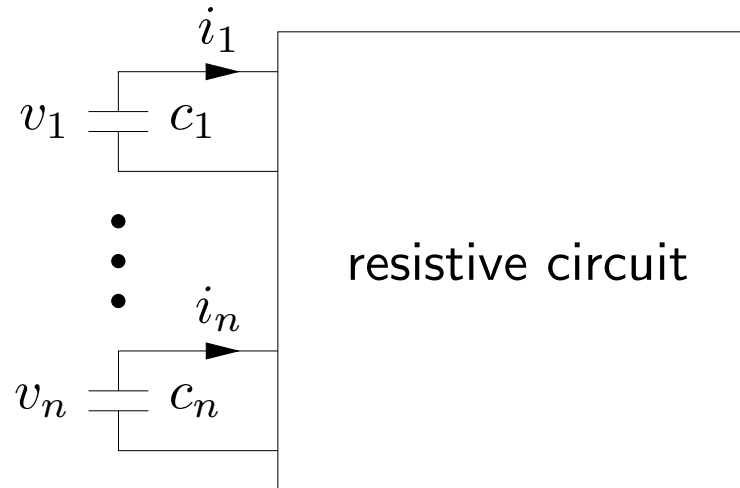
$$v_i^T (Av_j) = \lambda_j v_i^T v_j = (Av_i)^T v_j = \lambda_i v_i^T v_j$$

so  $(\lambda_i - \lambda_j)v_i^T v_j = 0$

for  $i \neq j$ ,  $\lambda_i \neq \lambda_j$ , hence  $v_i^T v_j = 0$

- in this case we can say: eigenvectors *are* orthogonal
- in general case ( $\lambda_i$  not distinct) we must say: eigenvectors *can be chosen* to be orthogonal

## Example: RC circuit



$$C_k \dot{v}_k = -i_k, \quad i = Gv$$

$G = G^T \in \mathbf{R}^{n \times n}$  is conductance matrix of resistive circuit

thus  $\dot{v} = -C^{-1}Gv$  where  $C = \mathbf{diag}(c_1, \dots, c_n)$

note  $-C^{-1}G$  is not symmetric



use state  $x_i = \sqrt{c_i}v_i$ , so

$$\dot{x} = C^{1/2}\dot{v} = -C^{-1/2}GC^{-1/2}x$$

where  $C^{1/2} = \mathbf{diag}(\sqrt{c_1}, \dots, \sqrt{c_n})$

we conclude:

- eigenvalues  $\lambda_1, \dots, \lambda_n$  of  $-C^{-1/2}GC^{-1/2}$  (hence,  $-C^{-1}G$ ) are real
- eigenvectors  $q_i$  (in  $x_i$  coordinates) can be chosen orthogonal
- eigenvectors in voltage coordinates,  $s_i = C^{-1/2}q_i$ , satisfy

$$-C^{-1}Gs_i = \lambda_i s_i, \quad s_i^T C s_i = \delta_{ij}$$

# Quadratic forms

a function  $f : \mathbf{R}^n \rightarrow \mathbf{R}$  of the form

$$f(x) = x^T A x = \sum_{i,j=1}^n A_{ij} x_i x_j$$

is called a *quadratic form*

in a quadratic form we may as well assume  $A = A^T$  since

$$x^T A x = x^T ((A + A^T)/2)x$$

$((A + A^T)/2)$  is called the *symmetric part* of  $A$ )

**uniqueness:** if  $x^T A x = x^T B x$  for all  $x \in \mathbf{R}^n$  and  $A = A^T$ ,  $B = B^T$ , then  $A = B$

# Examples

- $\|Bx\|^2 = x^T B^T Bx$
- $\sum_{i=1}^{n-1} (x_{i+1} - x_i)^2$
- $\|Fx\|^2 - \|Gx\|^2$

sets defined by quadratic forms:

- $\{ x \mid f(x) = a \}$  is called a *quadratic surface*
- $\{ x \mid f(x) \leq a \}$  is called a *quadratic region*

# Inequalities for quadratic forms

suppose  $A = A^T$ ,  $A = Q\Lambda Q^T$  with eigenvalues sorted so  $\lambda_1 \geq \dots \geq \lambda_n$

$$\begin{aligned}x^T Ax &= x^T Q\Lambda Q^T x \\ &= (Q^T x)^T \Lambda (Q^T x) \\ &= \sum_{i=1}^n \lambda_i (q_i^T x)^2 \\ &\leq \lambda_1 \sum_{i=1}^n (q_i^T x)^2 \\ &= \lambda_1 \|x\|^2\end{aligned}$$

*i.e.*, we have  $x^T Ax \leq \lambda_1 x^T x$

similar argument shows  $x^T Ax \geq \lambda_n \|x\|^2$ , so we have

$$\lambda_n x^T x \leq x^T Ax \leq \lambda_1 x^T x$$

sometimes  $\lambda_1$  is called  $\lambda_{\max}$ ,  $\lambda_n$  is called  $\lambda_{\min}$

note also that

$$q_1^T A q_1 = \lambda_1 \|q_1\|^2, \quad q_n^T A q_n = \lambda_n \|q_n\|^2,$$

so the inequalities are tight

# Positive semidefinite and positive definite matrices

suppose  $A = A^T \in \mathbf{R}^{n \times n}$

we say  $A$  is *positive semidefinite* if  $x^T Ax \geq 0$  for all  $x$

- denoted  $A \geq 0$  (and sometimes  $A \succeq 0$ )
- $A \geq 0$  if and only if  $\lambda_{\min}(A) \geq 0$ , *i.e.*, all eigenvalues are nonnegative
- **not** the same as  $A_{ij} \geq 0$  for all  $i, j$

we say  $A$  is *positive definite* if  $x^T Ax > 0$  for all  $x \neq 0$

- denoted  $A > 0$
- $A > 0$  if and only if  $\lambda_{\min}(A) > 0$ , *i.e.*, all eigenvalues are positive

# Matrix inequalities

- we say  $A$  is *negative semidefinite* if  $-A \geq 0$
- we say  $A$  is *negative definite* if  $-A > 0$
- otherwise, we say  $A$  is *indefinite*

**matrix inequality:** if  $B = B^T \in \mathbf{R}^n$  we say  $A \geq B$  if  $A - B \geq 0$ ,  $A < B$  if  $B - A > 0$ , etc.

for example:

- $A \geq 0$  means  $A$  is positive semidefinite
- $A > B$  means  $x^T A x > x^T B x$  for all  $x \neq 0$

many properties that you'd guess hold actually do, *e.g.*,

- if  $A \geq B$  and  $C \geq D$ , then  $A + C \geq B + D$
- if  $B \leq 0$  then  $A + B \leq A$
- if  $A \geq 0$  and  $\alpha \geq 0$ , then  $\alpha A \geq 0$
- $A^2 \geq 0$
- if  $A > 0$ , then  $A^{-1} > 0$

matrix inequality is only a *partial order*: we can have

$$A \not\geq B, \quad B \not\geq A$$

(such matrices are called *incomparable*)

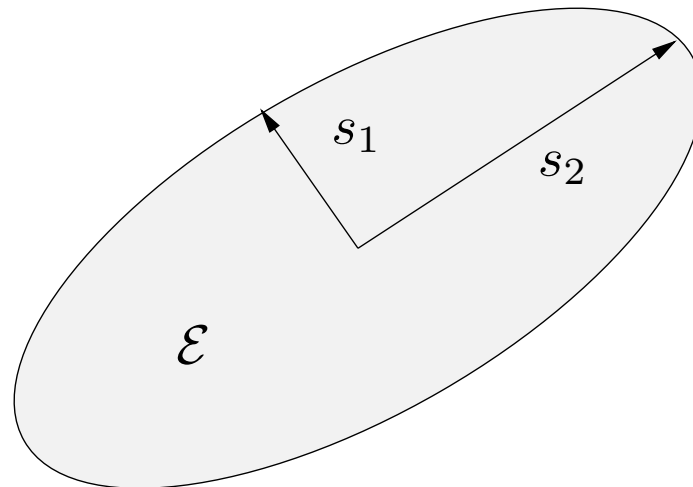


# Ellipsoids

if  $A = A^T > 0$ , the set

$$\mathcal{E} = \{ x \mid x^T A x \leq 1 \}$$

is an *ellipsoid* in  $\mathbf{R}^n$ , centered at 0



semi-axes are given by  $s_i = \lambda_i^{-1/2} q_i$ , *i.e.*:

- eigenvectors determine directions of semiaxes
- eigenvalues determine lengths of semiaxes

note:

- in direction  $q_1$ ,  $x^T A x$  is *large*, hence ellipsoid is *thin* in direction  $q_1$
- in direction  $q_n$ ,  $x^T A x$  is *small*, hence ellipsoid is *fat* in direction  $q_n$
- $\sqrt{\lambda_{\max}/\lambda_{\min}}$  gives maximum *eccentricity*

if  $\tilde{\mathcal{E}} = \{ x \mid x^T B x \leq 1 \}$ , where  $B > 0$ , then  $\mathcal{E} \subseteq \tilde{\mathcal{E}} \iff A \geq B$

# Gain of a matrix in a direction

suppose  $A \in \mathbf{R}^{m \times n}$  (not necessarily square or symmetric)

for  $x \in \mathbf{R}^n$ ,  $\|Ax\|/\|x\|$  gives the *amplification factor* or *gain* of  $A$  in the direction  $x$

obviously, gain varies with direction of input  $x$

## questions:

- what is maximum gain of  $A$   
(and corresponding maximum gain direction)?
- what is minimum gain of  $A$   
(and corresponding minimum gain direction)?
- how does gain of  $A$  vary with direction?

# Matrix norm

the maximum gain

$$\max_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

is called the *matrix norm* or *spectral norm* of  $A$  and is denoted  $\|A\|$

$$\max_{x \neq 0} \frac{\|Ax\|^2}{\|x\|^2} = \max_{x \neq 0} \frac{x^T A^T A x}{\|x\|^2} = \lambda_{\max}(A^T A)$$

so we have  $\|A\| = \sqrt{\lambda_{\max}(A^T A)}$

similarly the minimum gain is given by

$$\min_{x \neq 0} \|Ax\|/\|x\| = \sqrt{\lambda_{\min}(A^T A)}$$

note that

- $A^T A \in \mathbf{R}^{n \times n}$  is symmetric and  $A^T A \geq 0$  so  $\lambda_{\min}, \lambda_{\max} \geq 0$
- ‘max gain’ input direction is  $x = q_1$ , eigenvector of  $A^T A$  associated with  $\lambda_{\max}$
- ‘min gain’ input direction is  $x = q_n$ , eigenvector of  $A^T A$  associated with  $\lambda_{\min}$

**example:**  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$

$$\begin{aligned} A^T A &= \begin{bmatrix} 35 & 44 \\ 44 & 56 \end{bmatrix} \\ &= \begin{bmatrix} 0.620 & 0.785 \\ 0.785 & -0.620 \end{bmatrix} \begin{bmatrix} 90.7 & 0 \\ 0 & 0.265 \end{bmatrix} \begin{bmatrix} 0.620 & 0.785 \\ 0.785 & -0.620 \end{bmatrix}^T \end{aligned}$$

then  $\|A\| = \sqrt{\lambda_{\max}(A^T A)} = 9.53$ :

$$\left\| \begin{bmatrix} 0.620 \\ 0.785 \end{bmatrix} \right\| = 1, \quad \left\| A \begin{bmatrix} 0.620 \\ 0.785 \end{bmatrix} \right\| = \left\| \begin{bmatrix} 2.18 \\ 4.99 \\ 7.78 \end{bmatrix} \right\| = 9.53$$

min gain is  $\sqrt{\lambda_{\min}(A^T A)} = 0.514$ :

$$\left\| \begin{bmatrix} 0.785 \\ -0.620 \end{bmatrix} \right\| = 1, \quad \left\| A \begin{bmatrix} 0.785 \\ -0.620 \end{bmatrix} \right\| = \left\| \begin{bmatrix} 0.46 \\ 0.14 \\ -0.18 \end{bmatrix} \right\| = 0.514$$

for all  $x \neq 0$ , we have

$$0.514 \leq \frac{\|Ax\|}{\|x\|} \leq 9.53$$

# Properties of matrix norm

- consistent with vector norm: matrix norm of  $a \in \mathbf{R}^{n \times 1}$  is  $\sqrt{\lambda_{\max}(a^T a)} = \sqrt{a^T a}$
- for any  $x$ ,  $\|Ax\| \leq \|A\| \|x\|$
- scaling:  $\|aA\| = |a| \|A\|$
- triangle inequality:  $\|A + B\| \leq \|A\| + \|B\|$
- definiteness:  $\|A\| = 0 \iff A = 0$
- norm of product:  $\|AB\| \leq \|A\| \|B\|$



# Singular value decomposition

more complete picture of gain properties of  $A$  given by *singular value decomposition* (SVD) of  $A$ :

$$A = U\Sigma V^T$$

where

- $A \in \mathbf{R}^{m \times n}$ ,  $\mathbf{Rank}(A) = r$
- $U \in \mathbf{R}^{m \times r}$ ,  $U^T U = I$
- $V \in \mathbf{R}^{n \times r}$ ,  $V^T V = I$
- $\Sigma = \mathbf{diag}(\sigma_1, \dots, \sigma_r)$ , where  $\sigma_1 \geq \dots \geq \sigma_r > 0$

with  $U = [u_1 \cdots u_r]$ ,  $V = [v_1 \cdots v_r]$ ,

$$A = U\Sigma V^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

- $\sigma_i$  are the (nonzero) *singular values* of  $A$
- $v_i$  are the *right or input singular vectors* of  $A$
- $u_i$  are the *left or output singular vectors* of  $A$

$$A^T A = (U\Sigma V^T)^T (U\Sigma V^T) = V\Sigma^2 V^T$$

hence:

- $v_i$  are eigenvectors of  $A^T A$  (corresponding to nonzero eigenvalues)
- $\sigma_i = \sqrt{\lambda_i(A^T A)}$  (and  $\lambda_i(A^T A) = 0$  for  $i > r$ )
- $\|A\| = \sigma_1$

similarly,

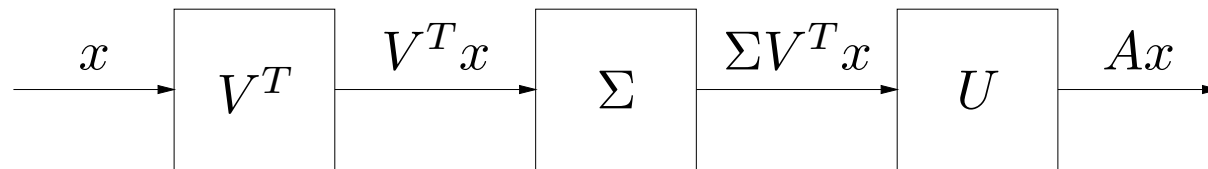
$$AA^T = (U\Sigma V^T)(U\Sigma V^T)^T = U\Sigma^2 U^T$$

hence:

- $u_i$  are eigenvectors of  $AA^T$  (corresponding to nonzero eigenvalues)
- $\sigma_i = \sqrt{\lambda_i(AA^T)}$  (and  $\lambda_i(AA^T) = 0$  for  $i > r$ )
  
- $u_1, \dots, u_r$  are orthonormal basis for  $\text{range}(A)$
- $v_1, \dots, v_r$  are orthonormal basis for  $\mathcal{N}(A)^\perp$

# Interpretations

$$A = U\Sigma V^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$



linear mapping  $y = Ax$  can be decomposed as

- compute coefficients of  $x$  along input directions  $v_1, \dots, v_r$
- scale coefficients by  $\sigma_i$
- reconstitute along output directions  $u_1, \dots, u_r$

difference with eigenvalue decomposition for symmetric  $A$ : input and output directions are *different*

- $v_1$  is most sensitive (highest gain) input direction
- $u_1$  is highest gain output direction
- $Av_1 = \sigma_1 u_1$

SVD gives clearer picture of gain as function of input/output directions

**example:** consider  $A \in \mathbf{R}^{4 \times 4}$  with  $\Sigma = \mathbf{diag}(10, 7, 0.1, 0.05)$

- input components along directions  $v_1$  and  $v_2$  are amplified (by about 10) and come out mostly along plane spanned by  $u_1, u_2$
- input components along directions  $v_3$  and  $v_4$  are attenuated (by about 10)
- $\|Ax\|/\|x\|$  can range between 10 and 0.05
- $A$  is nonsingular
- for some applications you might say  $A$  is *effectively* rank 2

**example:**  $A \in \mathbf{R}^{2 \times 2}$ , with  $\sigma_1 = 1$ ,  $\sigma_2 = 0.5$

- resolve  $x$  along  $v_1, v_2$ :  $v_1^T x = 0.5$ ,  $v_2^T x = 0.6$ , *i.e.*,  $x = 0.5v_1 + 0.6v_2$
- now form  $Ax = (v_1^T x)\sigma_1 u_1 + (v_2^T x)\sigma_2 u_2 = (0.5)(1)u_1 + (0.6)(0.5)u_2$

